



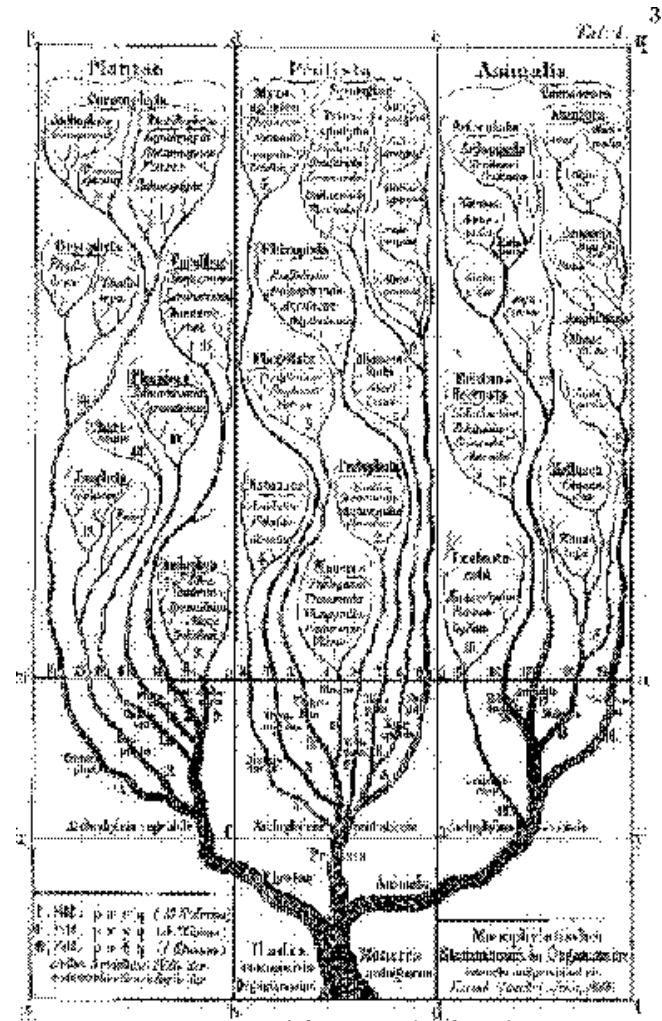
Geometry of phylogenetics

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phylogenetics

Phylogenetics:
reconstructing
historical relation
between species
by analyzing their
present features
and putting their
common ancestors
in a diagram
which forms a tree.
[e.g. Hackel, 1866]

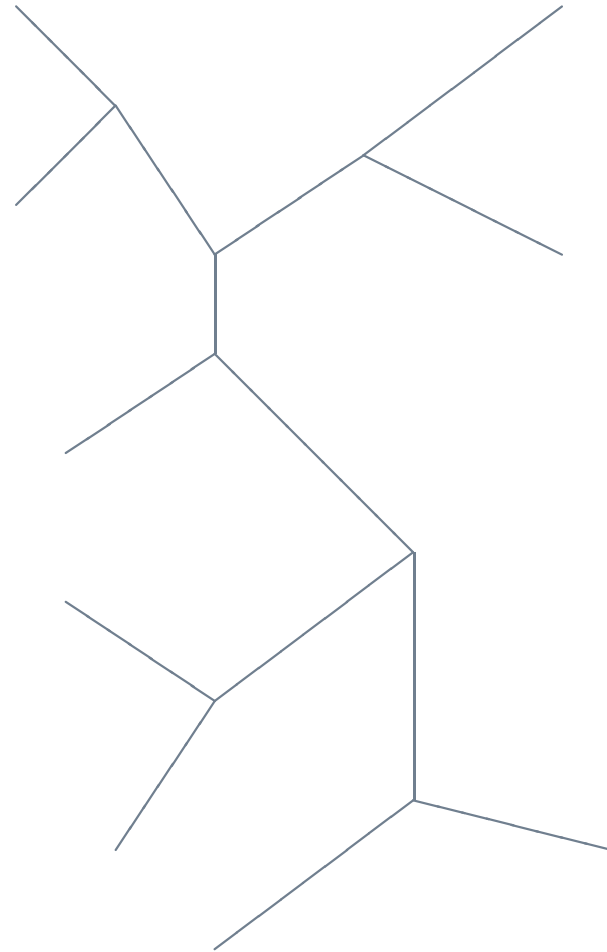


trees, sockets and networks

Consider a tree \mathcal{T} which has $d + 1$ leaves \mathcal{L} , $d - 1$ inner trivalent nodes \mathcal{N} and $2d - 1$ edges \mathcal{E} ; *socket* is a subset of \mathcal{L} which has even number of elements; *path* in \mathcal{T} is a connected union of edges, *network* is a set of non-meeting paths in \mathcal{T} with ends in \mathcal{L}

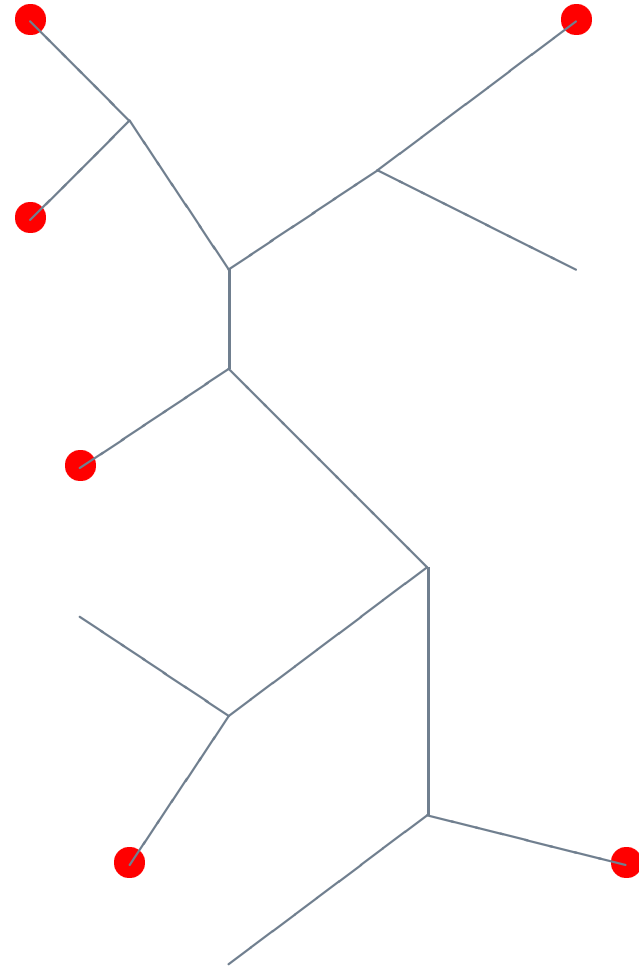
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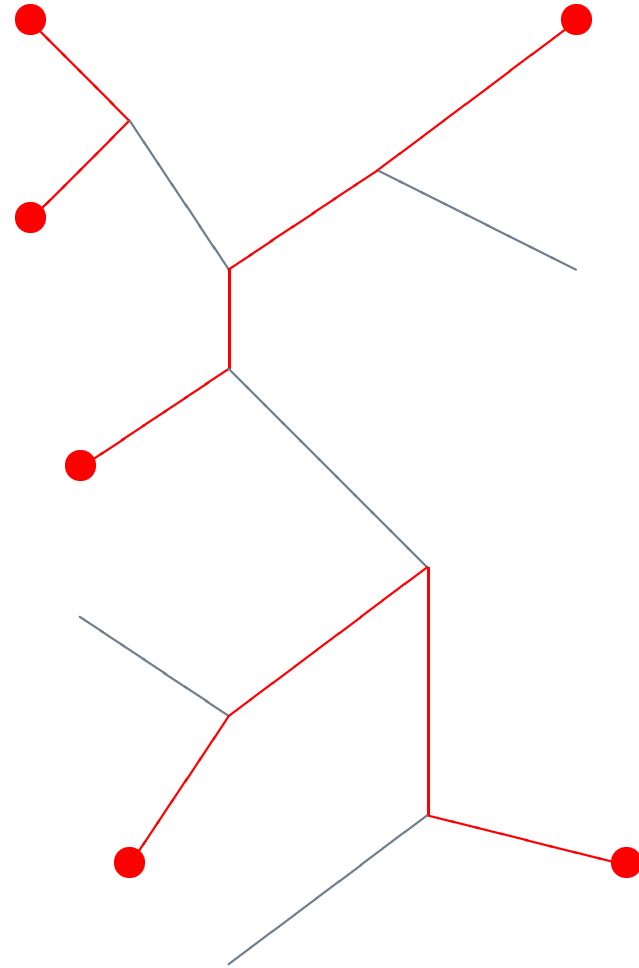
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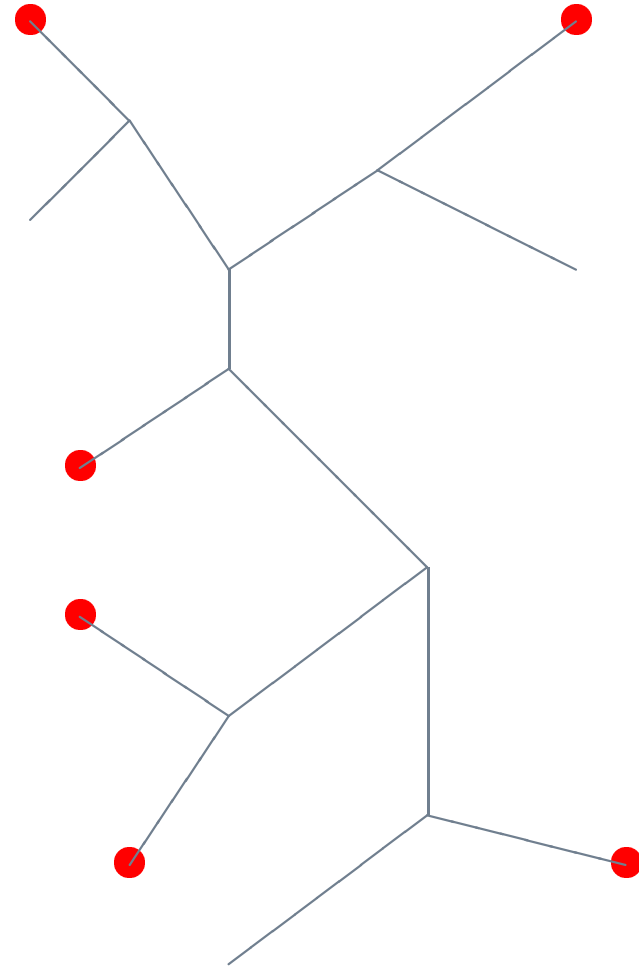
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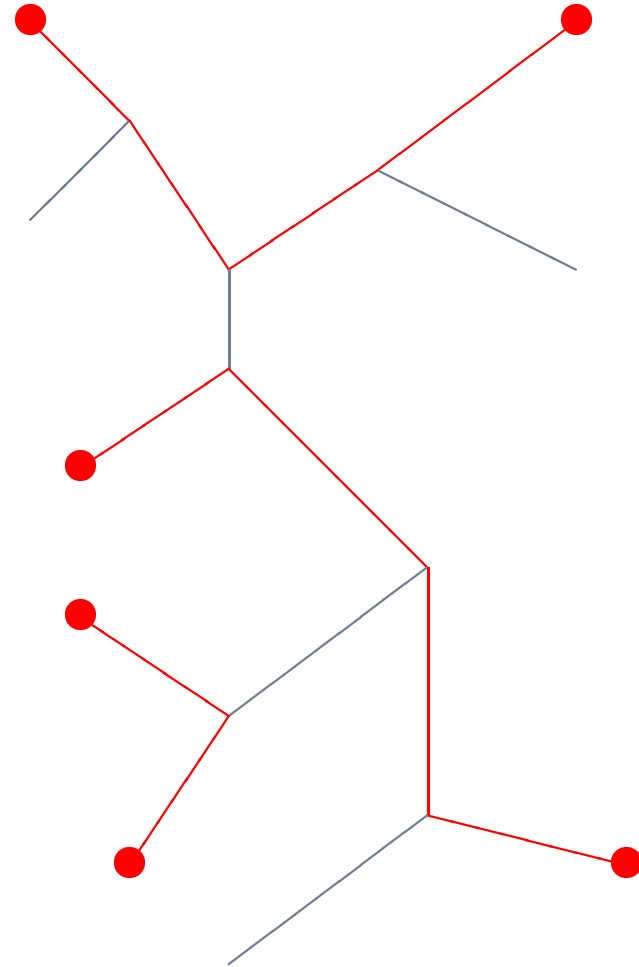
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tree \rightarrow variety, first view

[lemma] There is a bijection between the set of sockets and networks, that is for every socket σ there exists a unique network $\mu(\sigma)$ whose end points are in σ

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For every edge $e \in \mathcal{E}$ we consider a \mathbb{P}_e^1 with homogeneous coordinates $[y_0^e, y_1^e]$. Moreover consider a projective space \mathbb{P}_Σ of dimension $2^d - 1$ with homogeneous coordinates $[z_\sigma]$ indexed by sockets of \mathcal{T} .

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Define rational map $\prod_{e \in \mathcal{E}} \mathbb{P}_e^1 \rightarrow \mathbb{P}_\Sigma$ such that

$$z_\sigma = \prod_{e \in \mu(\sigma)} y_1^e \cdot \prod_{e \notin \mu(\sigma)} y_0^e$$

The **model of the tree**, $X(\mathcal{T}) \subset \mathbb{P}_\Sigma$, is the closure of the image of this map, $\dim X(\mathcal{T}) = 2d - 1$.

first examples

Leaves of \mathcal{T} are labeled by numbers $1, \dots, d + 1$ and sockets are denoted by 0/1 of length $d + 1$.

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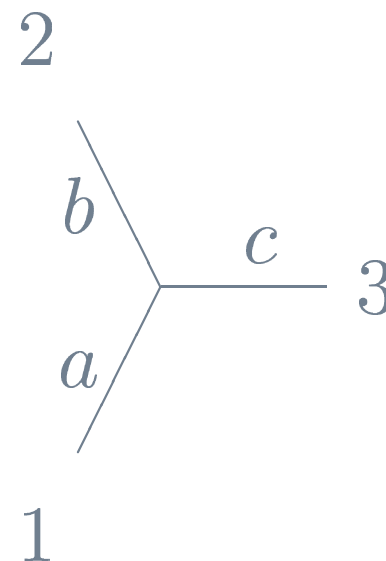
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Tripod tree model:

$$\mathbb{P}_a^1 \times \mathbb{P}_b^1 \times \mathbb{P}_c^1 \rightarrow \mathbb{P}^3$$

$$\begin{aligned} z_{000} &= y_0^a y_0^b y_0^c & z_{110} &= y_1^a y_1^b y_0^c \\ z_{101} &= y_1^a y_0^b y_1^c & z_{011} &= y_0^a y_1^b y_1^c \end{aligned}$$

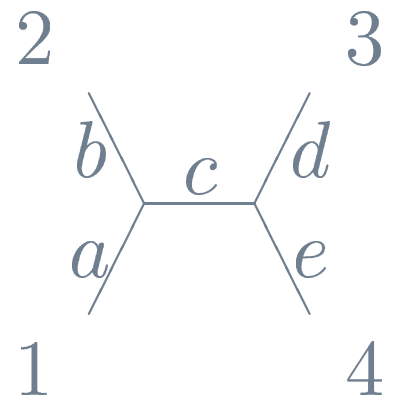


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Leaves of \mathcal{T} are labeled by numbers $1, \dots, d + 1$ and sockets are denoted by 0/1 of length $d + 1$.

Four leaf tree model in \mathbb{P}^7

$$\begin{array}{ll} z_{0000} = y_0^a y_0^b y_0^c y_0^d y_0^e & z_{1111} = y_1^a y_1^b y_0^c y_1^d y_1^e \\ z_{1100} = y_1^a y_1^b y_0^c y_0^d y_0^e & z_{0011} = y_0^a y_0^b y_0^c y_1^d y_1^e \\ z_{1010} = y_1^a y_0^b y_1^c y_1^d y_0^e & z_{1001} = y_1^a y_0^b y_1^c y_0^d y_1^e \\ z_{0110} = y_0^a y_1^b y_1^c y_1^d y_0^e & z_{0101} = y_0^a y_1^b y_1^c y_0^d y_1^e \end{array}$$



first examples

Leaves of \mathcal{T} are labeled by numbers $1, \dots, d+1$ and sockets are denoted by 0/1 of length $d+1$.

Therefore $X(\searrow) \simeq \mathbb{P}^3$ and $X(\searrow\swarrow)$ is a complete intersection in \mathbb{P}^7 :

$$z_{0000}z_{1111} = z_{1100}z_{0011} \quad z_{1010}z_{0101} = z_{1001}z_{0110}$$

The diagrammatic equations illustrate the algebraic identities above. In the first equation, the left side shows a tree with two sockets and two leaves, where the left socket and its leaf are grey, and the right socket and its leaf are red. This is equal to the sum of two trees: one with a red left socket and leaf, and a grey right socket and leaf; the other with a grey left socket and leaf, and a red right socket and leaf. The second equation is similar, but the two sockets and their leaves are connected by a horizontal line, and the left side shows two such trees with different colorings (red-left/grey-right and grey-left/red-right), which is equal to the sum of two trees with one red and one grey socket and leaf.

binary Markov process on tree

Fix a root r in tree \mathcal{T} : this implies a partial order $<$ on the set of vertexes $\mathcal{V} = \mathcal{L} \cup \mathcal{N}$. To each vertex $v \in \mathcal{V}$ assign a random variable ξ_v which takes value in $\{\alpha_1, \alpha_2\}$.

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Variables ξ_v determine a Markov process on \mathcal{T} if (intuitively) the value of ξ_v depends only on the value of ξ_u , where u is the node immediately preceding v .

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For each edge $e = \langle u, v \rangle$ bounded by vertexes $u < v$ define the transition matrix A^e :

$$A_{ij}^e = P(\xi_v = \alpha_j | \xi_u = \alpha_i)$$

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and set the probability of the variable ξ_r at the root: $P_i^r = P(\xi_r = \alpha_i)$

from Markov to phylogenetics

For a Markov process on a rooted tree \mathcal{T} as above

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For a Markov process on a rooted tree \mathcal{T} as above and any function $\mathcal{V} \ni v \rightarrow \rho(v) \in \{1, 2\}$

$$P\left(\bigwedge_{v \in \mathcal{V}} \xi_v = \alpha_{\rho(v)}\right) = P_{\rho(r)}^r \cdot \prod_{e = \langle u, v \rangle \in \mathcal{E}} A_{\rho(u)\rho(v)}^e$$

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where the sum is taken over all $\hat{\rho} : \mathcal{V} \rightarrow \{1, 2\}$ which extend ρ .

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where the sum is taken over all $\hat{\rho} : \mathcal{V} \rightarrow \{1, 2\}$ which extend ρ . Phylogenetics: understand

the shape of \mathcal{T} by looking at the distribution of

$$P\left(\bigwedge_{v \in \mathcal{L}} \xi_v = \alpha_{\rho(v)}\right).$$

tree \rightarrow variety, Markov view

Phylogenetics wants to understand the locus of possible probability values of a Markov process on a fixed tree \mathcal{T} :

$$\mathcal{X}(\mathcal{T}) :=$$

$$\{\zeta_\rho = P(\bigwedge_{v \in \mathcal{L}} \xi_v = \alpha_{\rho(v)}) : A_{ij}^e, P_i^r \text{ are arbitrary}\}$$

in the simplex with coordinates ζ_ρ where $\zeta_\rho \geq 0$,
 $\sum_\rho \zeta_\rho = 1$.

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note: these assumptions are very special but then incidently we have

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[theorem: Sturmfels, Sullivant] Then after suitable change of coordinates (and identifying spaces) the varieties $\mathcal{X}(\mathcal{T})$ and $X(\mathcal{T})$ coincide.

tree \rightarrow variety, via quotients

On \mathbb{P}^3 with homogeneous coordinates $[z_{000}, z_{110}, z_{101}, z_{011}]$ take three actions of \mathbb{C}^* whose weights are determined by socket 0/1 sequence:

$$\lambda_1(t)[z_{000}, z_{110}, z_{101}, z_{011}] = [z_{000}, tz_{110}, tz_{101}, z_{011}]$$

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Trivalent trees are built from tripods by identifying edges of leaves:

$$\begin{array}{c} 2a \\ \diagdown \\ \text{---} 3a \\ \diagup \\ 1a \end{array} \text{---} \begin{array}{c} 2b \\ \diagup \\ \text{---} 3b \\ \diagdown \\ 1b \end{array} = \begin{array}{c} 2a \\ \diagdown \\ \text{---} \\ \diagup \\ 1a \end{array} \begin{array}{c} 2b \\ \diagup \\ \text{---} \\ \diagdown \\ 1b \end{array}$$

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Take quotient $\mathbb{P}_a^3 \times \mathbb{P}_b^3 // (\lambda_{3a} \cdot \lambda_{3b}^{-1})$

$$\begin{aligned} &([z_{000}^a, z_{110}^a, z_{101}^a, z_{011}^a], [z_{000}^b, z_{110}^b, z_{101}^b, z_{011}^b]) \rightarrow \\ &[z_{000}^a z_{000}^b, z_{000}^a z_{110}^b, z_{110}^a z_{000}^b, z_{110}^a z_{110}^b, z_{101}^a z_{101}^b, \\ & z_{101}^a z_{011}^b, z_{011}^a z_{101}^b, z_{011}^a z_{011}^b] \end{aligned}$$

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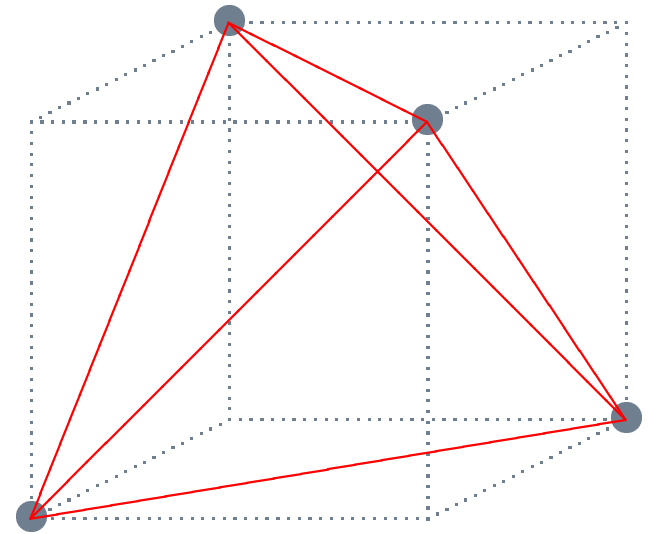
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The variety $X(\mathcal{T})$ is obtained as a quotient of product of \mathbb{P}^3 indexed by inner nodes by a torus identifying legs of tripods to inner edges of the tree.

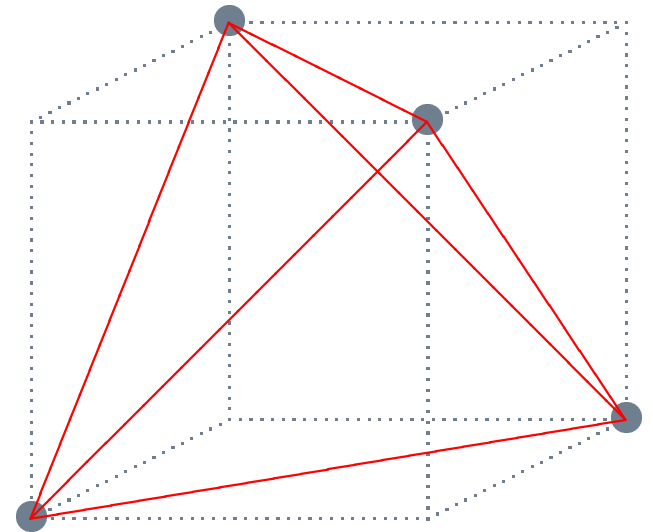
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In toric geometry \mathbb{P}^3 can be viewed as a tetrahedron inscribed in a cube with the three principal directions of projection representing respective \mathbb{C}^* actions.



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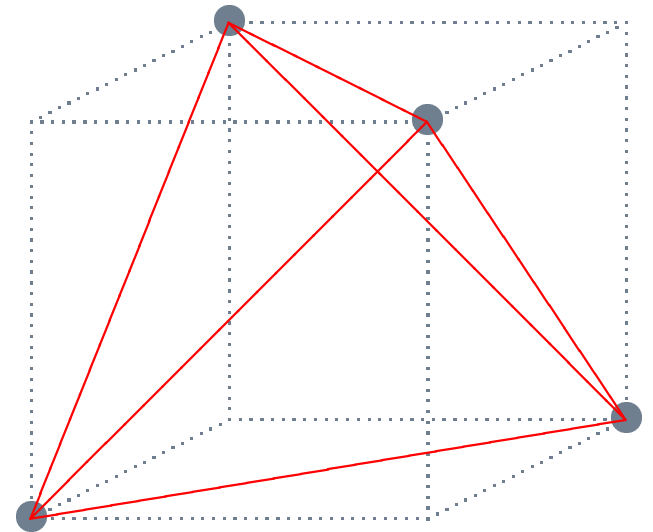
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Thus toric varieties associated to trees can be viewed as the fiber products of such tetrahedra.

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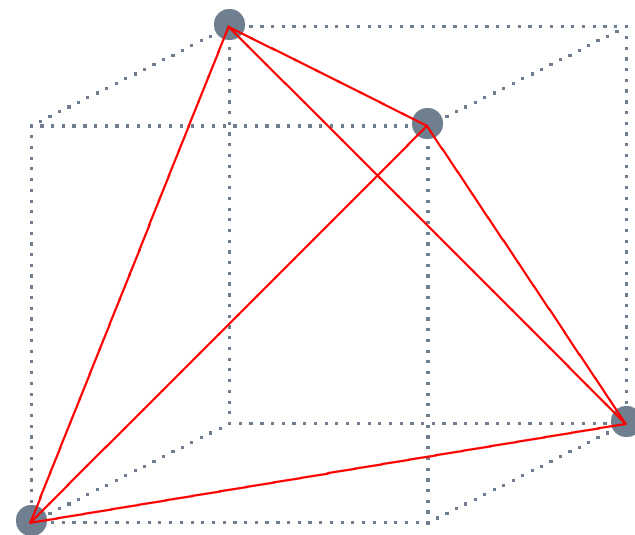
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Surprise: Hilbert-Ehrhart polynomial does not depend on the shape of $X(\mathcal{T})$.

Hilbert-Ehrhart: ★ product

For a positive integer n let $[n] = \{0, \dots, n\}$.

Function $f : [n] \rightarrow \mathbb{Z}$ is symmetric if for every $k \in [n]$ it holds $f(k) = f(n - k)$.

By $\mathbf{1} : [n] \rightarrow \mathbb{Z}$ denote the unit function.

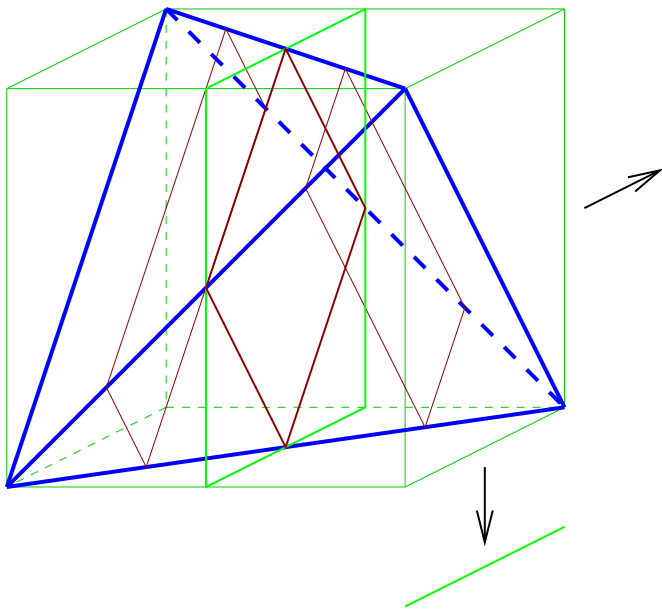
If $f_1, f_2 : [n] \rightarrow \mathbb{Z}$ are symmetric functions then we define their symmetric product $f_1 \star f_2 : [n] \rightarrow \mathbb{Z}$ such that for $k \leq n/2$:

$$(f_1 \star f_2)(k) = 2 \cdot \left(\sum_{i=0}^{k-1} \sum_{j=0}^i f_1(i) f_2(k + i - 2j) \right) + \left(\sum_{i=k}^{n-k} \sum_{j=0}^k f_1(i) f_2(k + i - 2j) \right)$$

geometric interpretation of \star

Consider the simplex Δ as in the picture

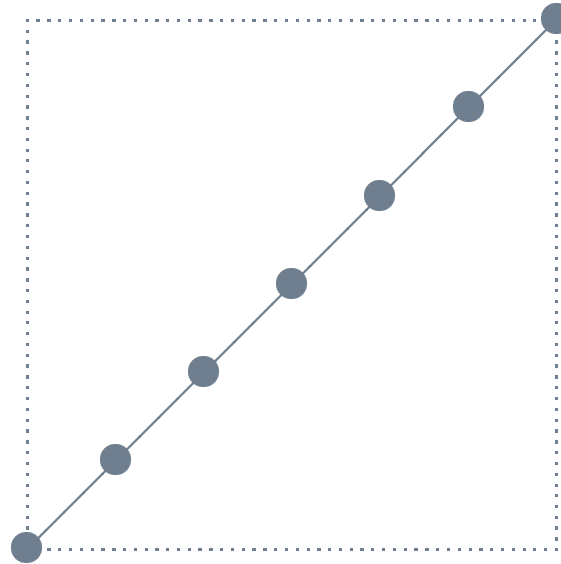
$(f_1 \star f_2)(k)$ is equal to the sum of products of f_1 and f_2 counted over points of lattice spanned by Δ in k -th slice of $n \cdot \Delta$



$(\mathbf{1} \star \mathbf{1})(k) = (k + 1)(n - k + 1)$ is the number of lattice points in k -th slice of $n \cdot \Delta$ and thus \star can be used to compute Hilbert-Ehrhart polynomial

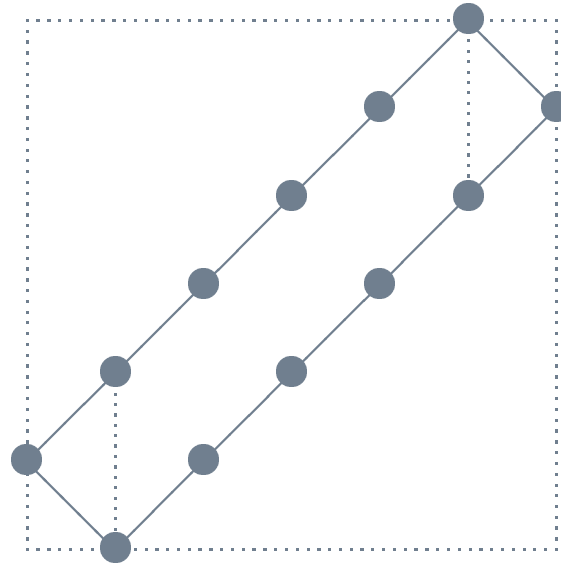
travel trough $6 \cdot \Delta$

$$k = 0$$

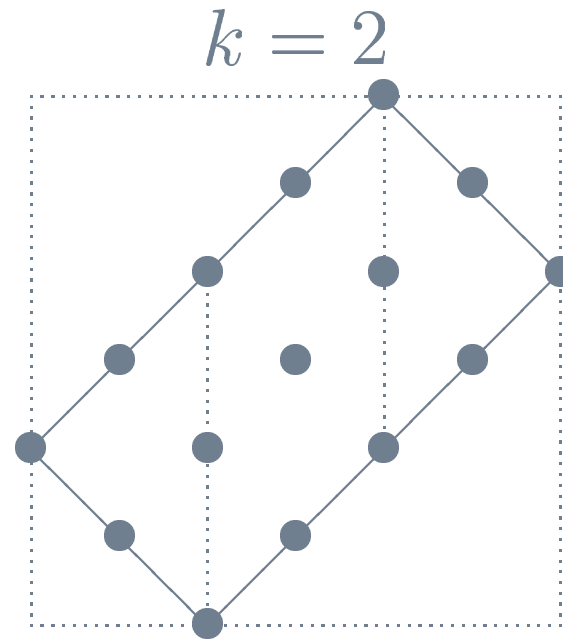


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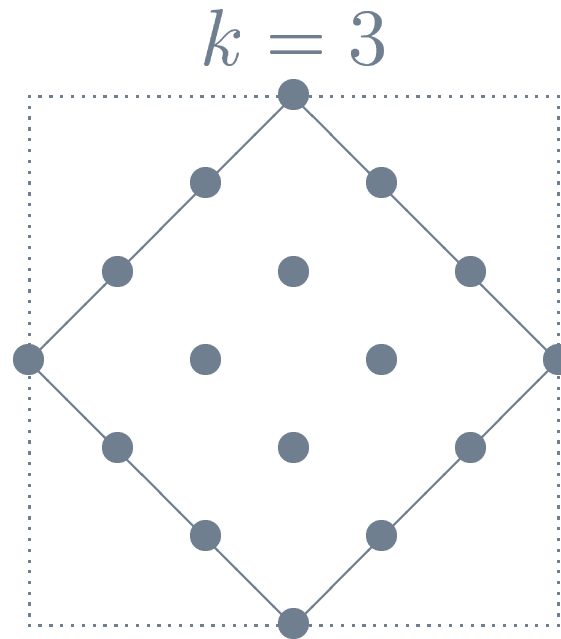
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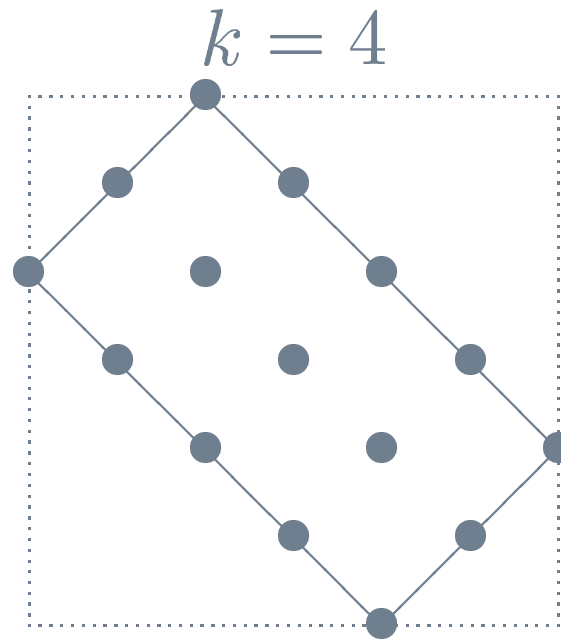
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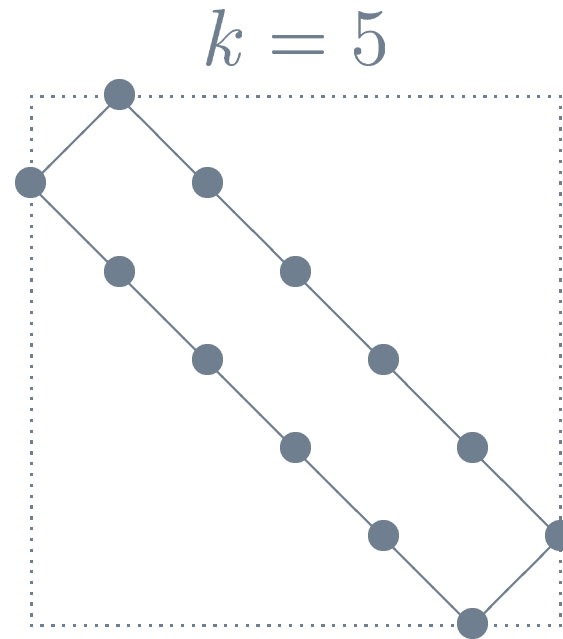
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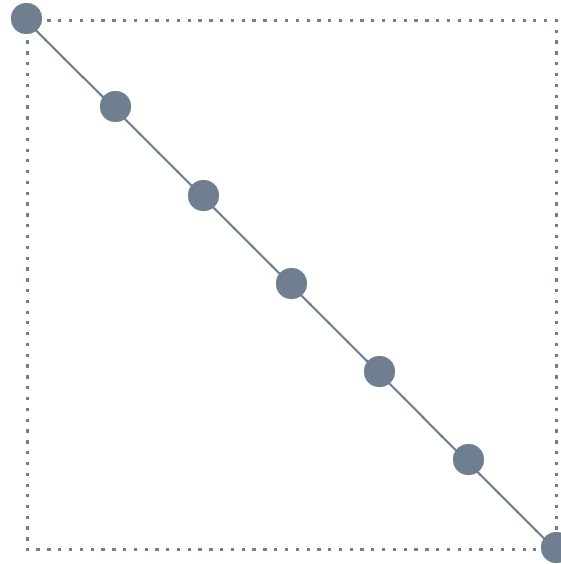


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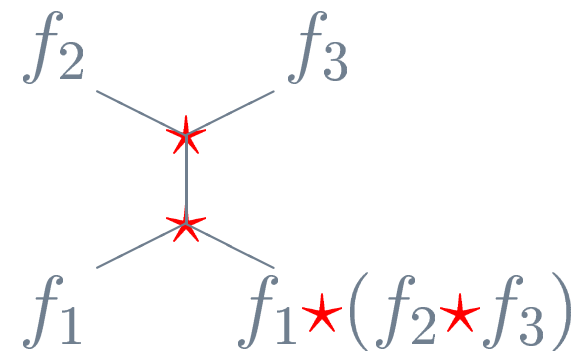
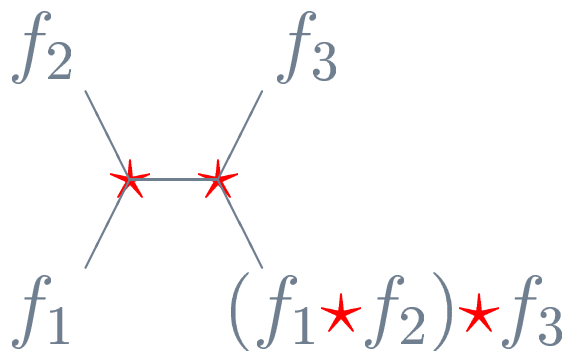
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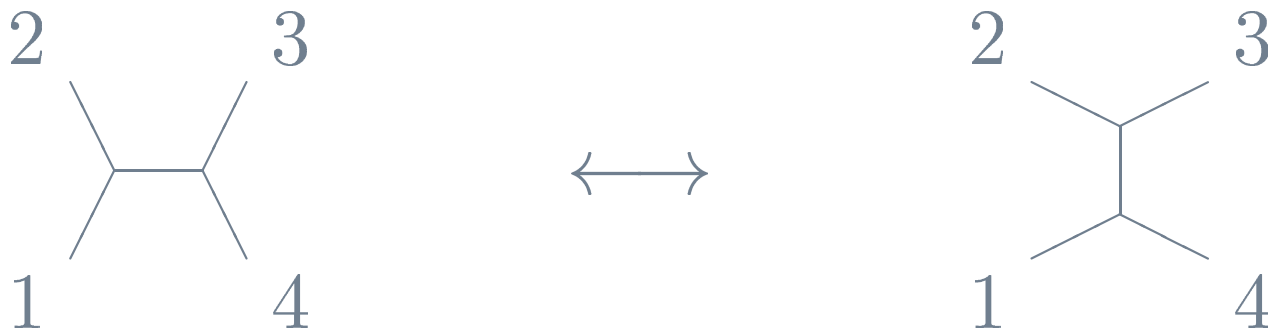


deforming $X(\mathcal{T})$ within \mathbb{P}_Σ

Recall that leaves of \mathcal{T} can be labeled by numbers $1, \dots, d + 1$ or, equivalently, given $d + 1$ points we can make them leaves of a (non-unique) tree \mathcal{T} .

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These varieties can be non-isomorphic **(one can check it)**, however they are in the same connected component of the Hilbert scheme of \mathbb{P}_Σ , that is

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[theorem] $X(\mathcal{T}_1)$ can be deformed to $X(\mathcal{T}_2)$ if only \mathcal{T}_1 and \mathcal{T}_2 have the same number of leaves.

proof: working dictionary

Translate the original problem into toric geometry

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tree

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variety

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tree

polytope

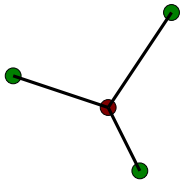
variety

understand the basic objects

proof: working dictionary

Translate the original problem into toric geometry

tree



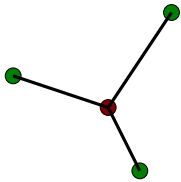
polytope

variety

proof: working dictionary

Translate the original problem into toric geometry

tree



polytope

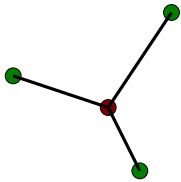
variety

\mathbb{P}^3

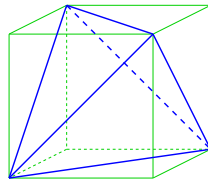
proof: working dictionary

Translate the original problem into toric geometry

tree



polytope



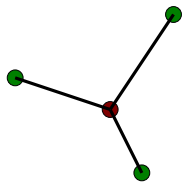
variety

\mathbb{P}^3

proof: working dictionary

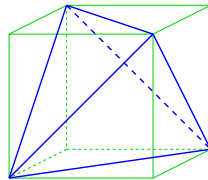
Translate the original problem into toric geometry

tree



a leaf

polytope



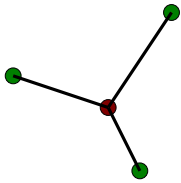
variety

\mathbb{P}^3

proof: working dictionary

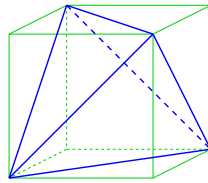
Translate the original problem into toric geometry

tree



a leaf

polytope



projection

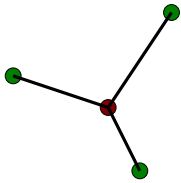
variety

\mathbb{P}^3

proof: working dictionary

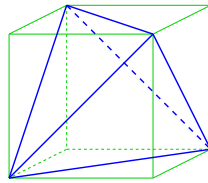
Translate the original problem into toric geometry

tree



a leaf

polytope



projection

variety

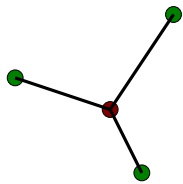
\mathbb{P}^3

\mathbb{C}^* action

proof: working dictionary

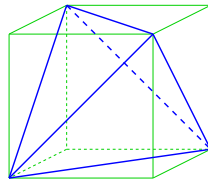
Translate the original problem into toric geometry

tree



a leaf

polytope

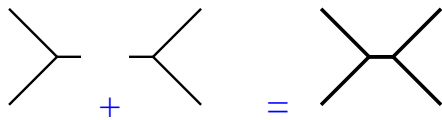


projection

variety

\mathbb{P}^3

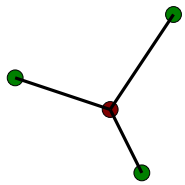
\mathbb{C}^* action



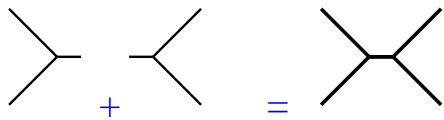
proof: working dictionary

Translate the original problem into toric geometry

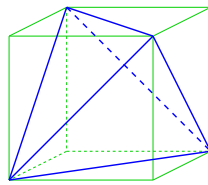
tree



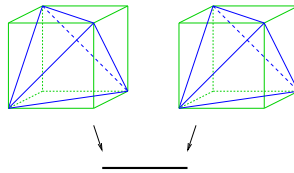
a leaf



polytope



projection



variety

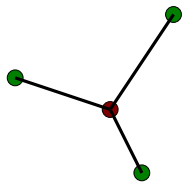
\mathbb{P}^3

\mathbb{C}^* action

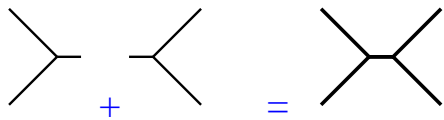
proof: working dictionary

Translate the original problem into toric geometry

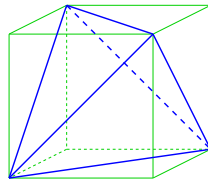
tree



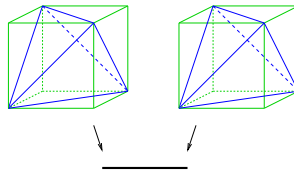
a leaf



polytope



projection



variety

\mathbb{P}^3

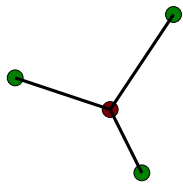
\mathbb{C}^* action

GIT quotient

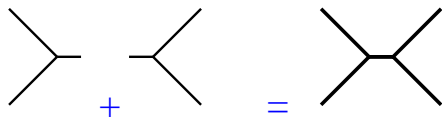
proof: working dictionary

Translate the original problem into toric geometry

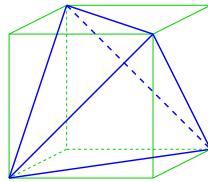
tree



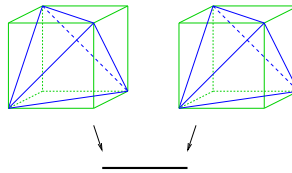
a leaf



polytope



projection



variety

\mathbb{P}^3

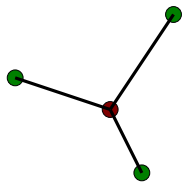
\mathbb{C}^* action

GIT quotient

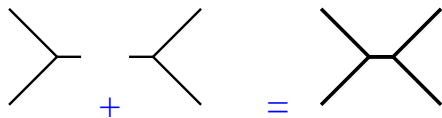
proof: working dictionary

Translate the original problem into toric geometry

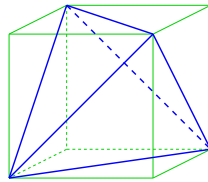
tree



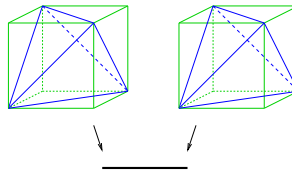
a leaf



polytope



projection



variety

\mathbb{P}^3

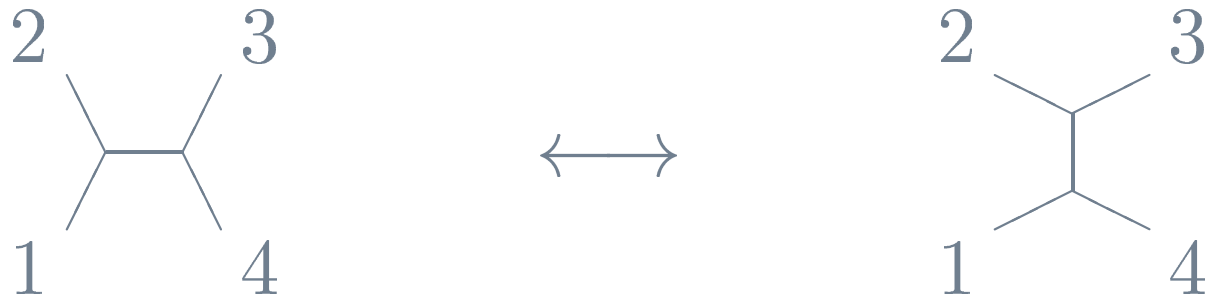
\mathbb{C}^* action

GIT quotient

deformation

proof: the idea

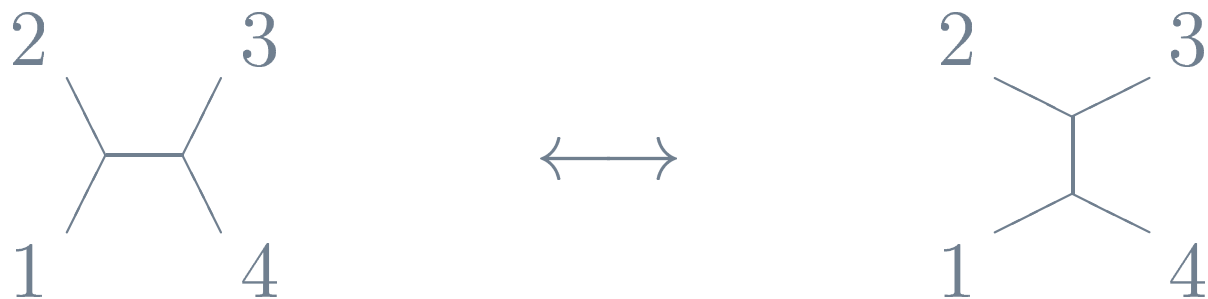
The mutation of a 4-leaf tree



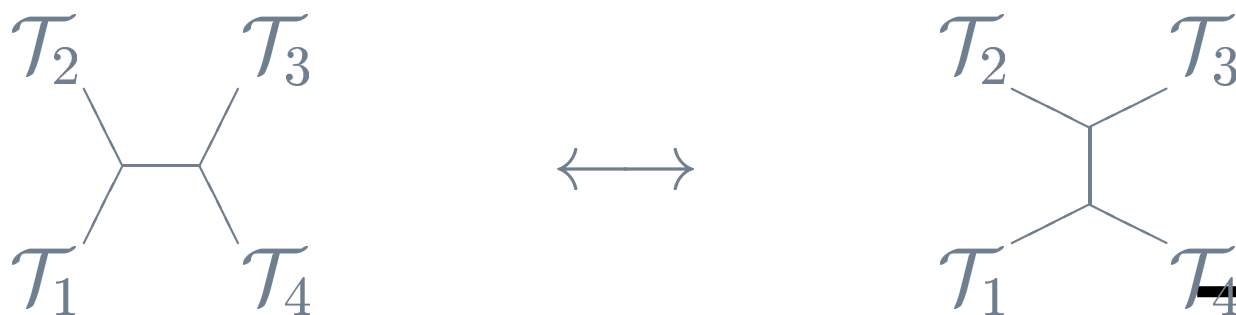
can be explicitly written as deformation which preserves the action of \mathbb{C}^* groups associated to leaves,

proof: the idea

The mutation of a 4-leaf tree



can be explicitly written as deformation which preserves the action of \mathbb{C}^* groups associated to leaves, thus via GIT quotient it can be extended to a mutation of any tree along any inner edge

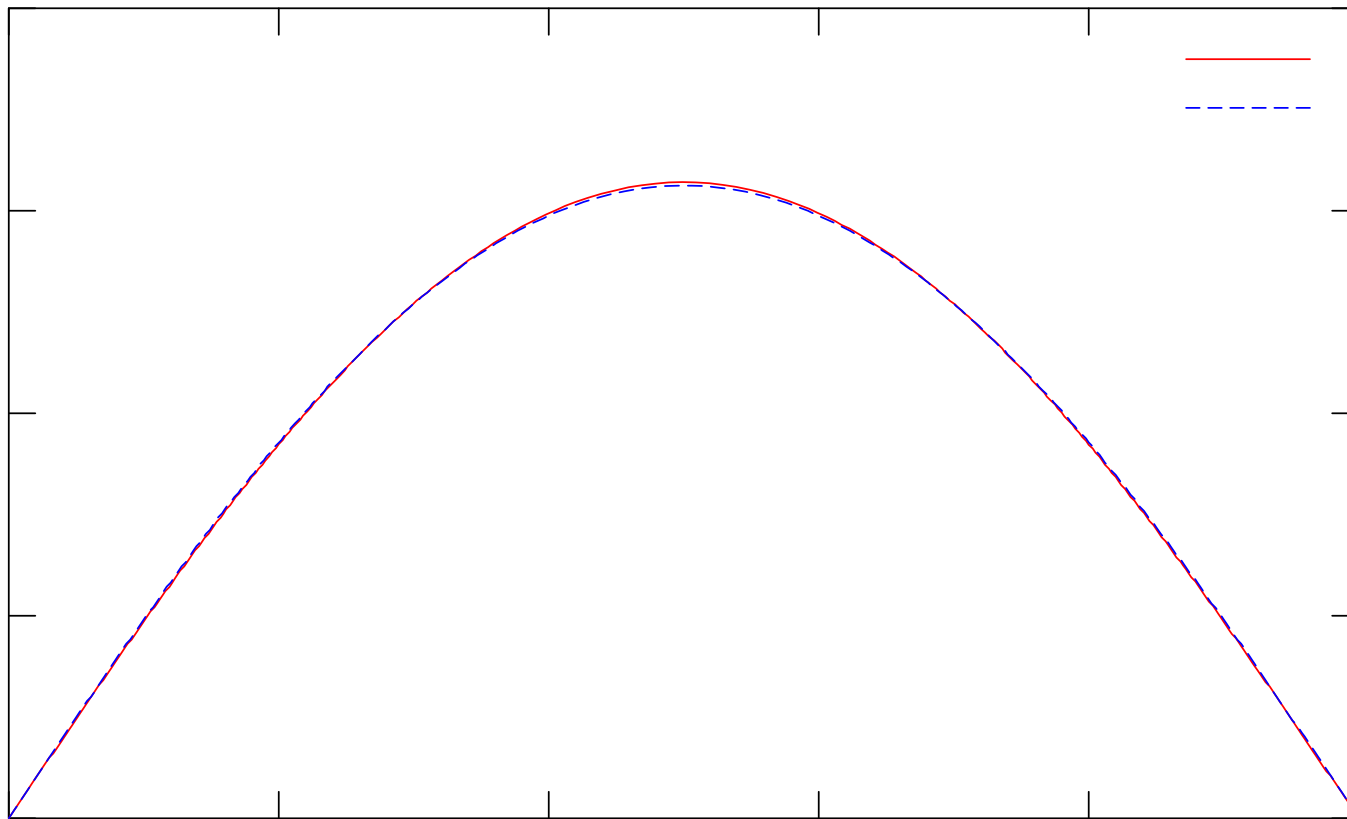


a problem to think about (1)

can one see the size a tree by looking at a leaf?

a problem to think about (1)

can one see the size a tree by looking at a leaf?



a problem to think about (2)

a symmetric model of four state system ACTG

a problem to think about (2)

a symmetric model of four state system ACTG
with transition matrix

$$\begin{pmatrix} a & b & c & d \\ b & a & d & c \\ c & d & a & b \\ d & c & b & a \end{pmatrix}$$

a problem to think about (2)

a symmetric model of four state system ACTG

0	0	0	0	0	0	0	0	0		1	0	0	1	0	0	0	0	0
1	0	0	0	0	0	1	0	0		0	0	0	1	0	0	1	0	0
0	1	0	0	1	0	0	0	0		0	1	0	0	0	0	0	1	0
0	0	0	0	1	0	0	1	0		0	0	1	0	0	1	0	0	0
0	0	1	0	0	0	0	0	1		0	0	0	0	0	1	0	0	1
1	0	0	0	1	0	0	0	1		1	0	0	0	0	1	0	1	0
0	1	0	1	0	0	0	0	1		0	1	0	0	0	1	1	0	0
0	0	1	1	0	0	0	1	0		0	0	1	0	1	0	1	0	0

a problem to think about (3)

the strand model of four state system ACTG

a problem to think about (3)

the strand model of four state system ACTG with transition matrix

$$\begin{pmatrix} a & b & c & d \\ e & f & g & h \\ h & g & f & e \\ d & c & b & a \end{pmatrix}$$